## **Outlier Detection in FMRI Time Series**

## Robert W Cox, PhD

Scientific and Statistical Computing Core
National Institute of Mental Health, Bethesda MD USA

**Goal**: Find outliers (wild points) in FMRI time series data.

**Synopsis**: Compute range of "usual" values, then find values outside this range.

**Step 1**: Compute median  $m(\mathbf{x})$  of each voxel time series  $v(\mathbf{x},t)$ .

⇒ This provides the middle of the "usual" range for each voxel **x**.

Step 2: Calculate clip level c such that  $c = 0.5 \cdot \text{median}\{m(\mathbf{x}): m > c\}$ .

 $\Rightarrow$  From now on, ignore voxels with  $m(\mathbf{x}) < c$  [as being too small and outside the brain].

**<u>Step 3</u>**: For each voxel time series, compute the

median-absolute- deviation:

 $MAD(\mathbf{x})=median_{f}\{|v(\mathbf{x},t)-m(\mathbf{x})|\}.$ 

**Step 4**: The "usual" range in each voxel  $\mathbf{x}$  is

[ $m(\mathbf{x})$ -a·MAD( $\mathbf{x}$ ),  $m(\mathbf{x})$ +a·MAD( $\mathbf{x}$ )] where a=Q<sup>-1</sup>(0.01/N)· $\sqrt{(\pi/2)}$ 

Q()=reversed Gaussian cdf N=length of time series

**Step 5**: For each time *t*, the number of outlying

voxels n(t) is counted at all brain voxels **x** 

(defined as in Step 2).

**Step 6**: The median  $n_{\text{med}}$  and MAD  $n_{\text{MAD}}$  of n(t)

are calculated.

 $\Rightarrow$  Any t with  $n(t) > n_{\text{med}} + 3.5 \cdot n_{\text{MAD}}$  is flagged as having an unusual number of outliers.

**Example**: Large counts at start are due to equilibration of  $M_{\tau}$ .

- ⇒ Spikes past t = 20 were due to intermittent problems with the RF system.
- ⇒ This hardware problem was discovered due to the outlier detection process.

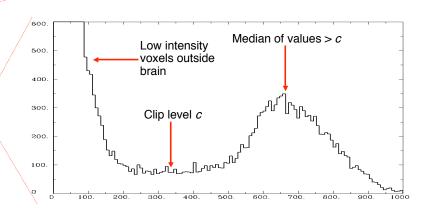
**Extension**: Look for outliers in  $\partial v(\mathbf{x},t)/\partial t$  as well.

**Software**: Now incorporated into **AFNI** package:

http://afni.nimh.nih.gov/afni



We use the median and median-absolute-deviation (MAD) statistics instead of mean and standard-deviation to prevent contamination by a few outliers.



- If the noise is Gaussian, then MAD =  $\sigma \cdot \sqrt{(2/\pi)}$ .
- A standard N(0,1) Gaussian will exceed  $Q^{-1}(p)$  with probability p.
- The threshold p = 0.01/N is chosen so that relatively few points will be counted as outliers if the noise is Gaussian.

